



## ***Knowledge Acquisition and Exploitation to Enhance STAP Performance***

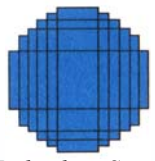
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**Dr. Charles Morgan**  
**Richard Pierro**  
**at: KASSPER Workshop**  
**Las Vegas, NV**  
**on: April 15, 2003**





# *Introduction*



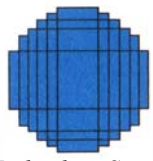
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- **STAP performance can be enhanced by exploiting thematically/spatially accurate and temporally current Digital Elevation Maps and Land Use/Land Cover databases**
  - Prefilter known clutter interference using covariance model
  - Exclude resolution cells from covariance estimate
  - Delimit surveillance area to where movers are likely
- **Extract knowledge that can be utilized in advanced STAP algorithms being developed by TSC and other KASSPER researchers**
  - Full and reduced dimension STAP architectures
- **Improve the accuracy of existing data bases through sensor signal processing**
  - DEM generation and strong scatterer geolocation from GMTI dwells
  - On/off-board SAR and Interferometric SAR image exploitation





# *DEM Generation Techniques*



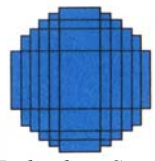
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- **More accurate DEMs can benefit STAP in several ways**
  - Improved mapping of known scatterers (discretes and movers) from object database into GMTI radar resolution cells for censoring
  - Better prediction of shadow regions and strong clutter backscattering geometries from sloped terrain to select secondary data sets
- **TSC is investigating both stereo and interferometric processing of GMTI clutter maps**
  - Stereo processing is based on correlating the GMTI clutter maps collected on two flight legs which have different elevation look angles
  - Interferometric processing is based on phase difference from elevation diversity provided by aircraft pitch and widely-spaced horizontal apertures
- **Utilizing SAR-based GMTI simulation to evaluate DEM generation accuracy for specific sites where SAR imagery is available**
  - Synthesize CPIs for arbitrary sensor platform position





# ***SAR-Based GMTI Simulation***



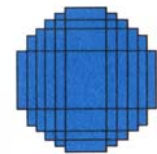
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- **TSC is utilizing ERIM IFSAR data to simulate GMTI clutter maps with high fidelity to evaluate DEM generation accuracy**
  - Provides registered SAR magnitude and terrain height with 2.5 m postings and Level 3 DTED accuracy
- **Model radar characteristics and 3-D geometry to produce data cubes (pulse x range x aperture)**
  - Slant range/squint angle
  - Antenna beam footprint
  - Range/Doppler resolution
  - Radar 3-D position and velocity
  - Multiple apertures
  - Internal clutter motion
  - Clutter amplitude distribution
  - Receiver noise
- **Data can also support investigation of techniques to exploit SAR imagery to enhance STAP performance**

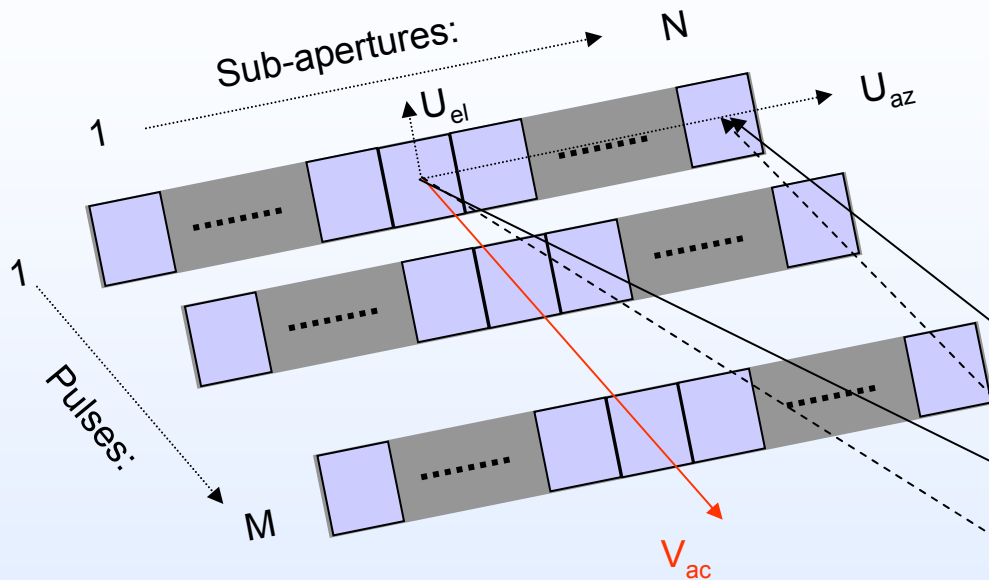




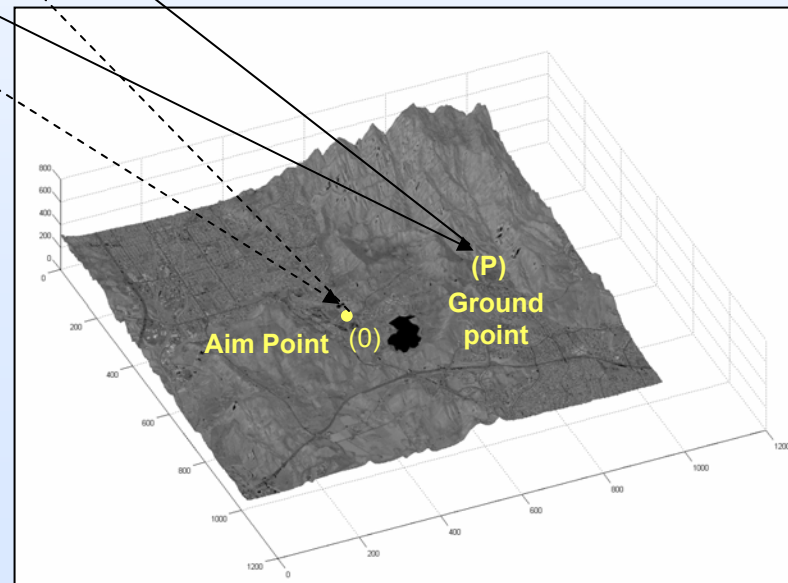
# Multiple Aperture Geometry for SAR-Based GMTI Simulation



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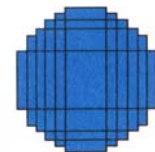


SAR Magnitude Overlayed on DEM

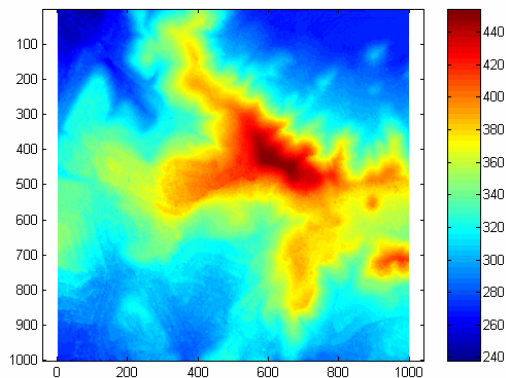




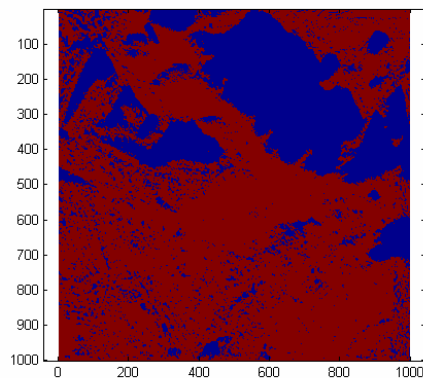
# *SAR-Based Simulation of Range-Doppler Maps (2.5m Postings)*



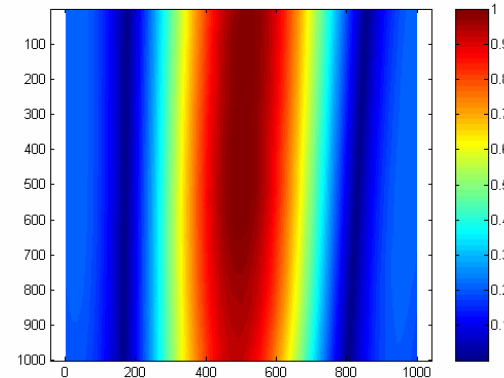
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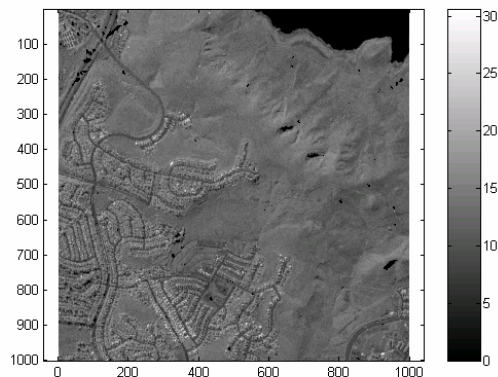
DTED (m)



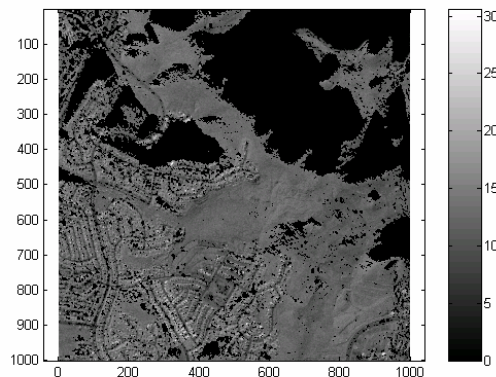
Shadowing (0,1)



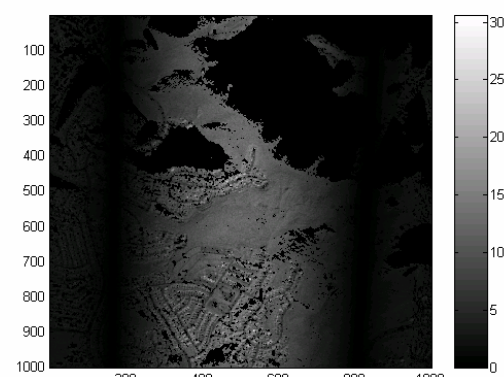
Antenna Gain (0-1)



SAR Magnitude (dB)



Shadowed Magnitude (dB)



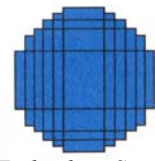
Shadowed Magnitude with  
Antenna Gain (dB)





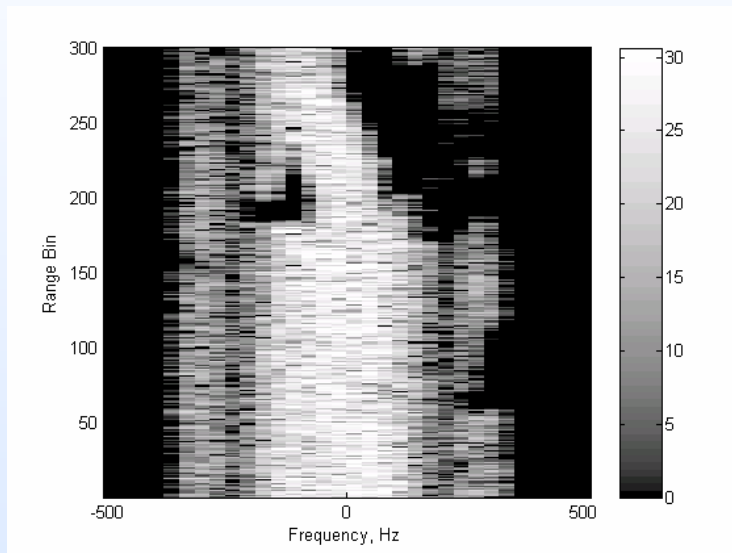


# *Effect of CPI Length on Simulated Range-Doppler Maps*

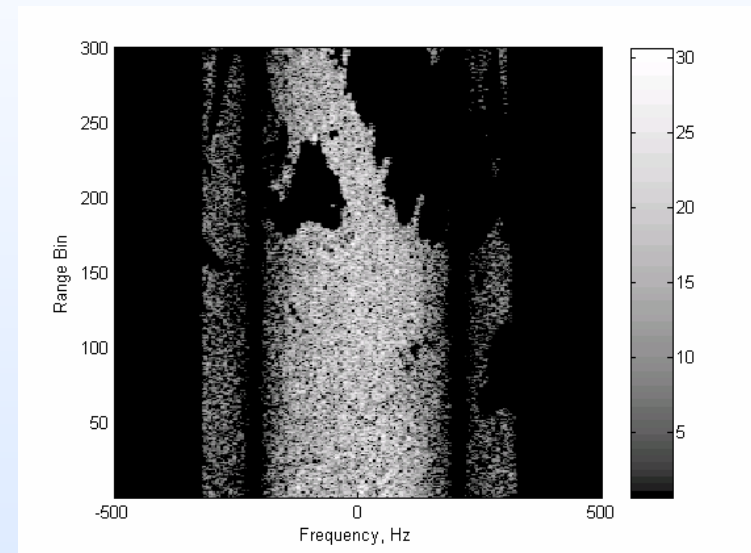


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- **GMTI map has similar features to original SAR image**
  - Can discern shadow regions and water boundaries when present
  - Different terrain types produce unique texture that can be exploited for map registration



32-Pulse CPI, 1 kHz PRF, Aperture #1

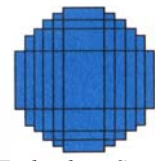


256-Pulse CPI, 1 kHz PRF, Aperture #1





# Stereo Processing Investigation



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- **Defined nominal race-track surveillance path for single or multiple platforms to cover region of interest**

- Altitude diversity to maximize elevation difference
- Beam tiling to cover region of interest

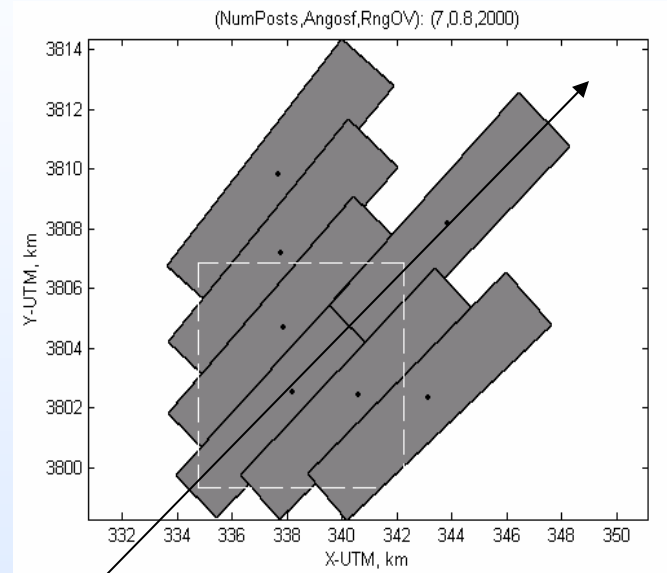
- **Investigating three modes of operation**

- Single set of MTI dwells at leg midpoint
- Average MTI dwells over entire leg
- Tomographic processing over entire leg to enhance cross-range resolution

- **Studying effect of dwell length and averaging on resultant DEM accuracy**

- Same GMTI dwell versus longer CPI
- Averaging reduces clutter scintillation and increases effective CNR
- Collecting statistics over multiple passes could also benefit STAP

Tiling of Region of Interest



LOS

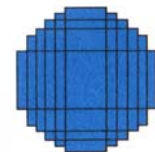
AIRCRAFT PATH







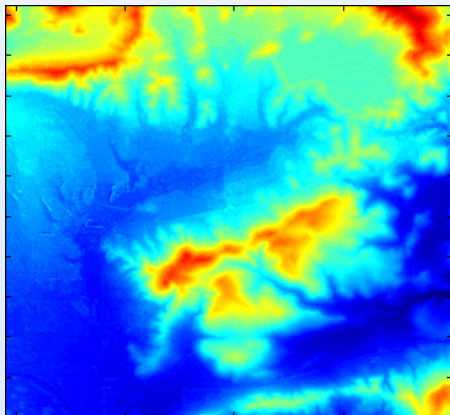
# Preliminary Stereo DEM Generation Results



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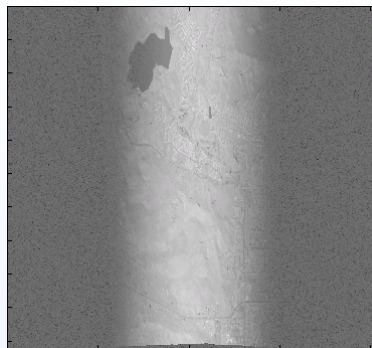


IFSAR MAGNITUDE

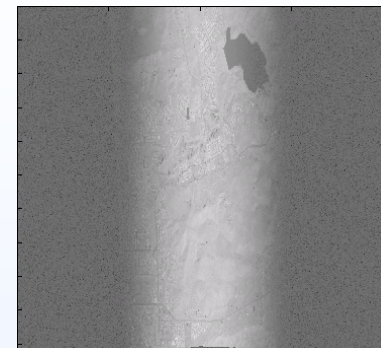


IFSAR HEIGHT

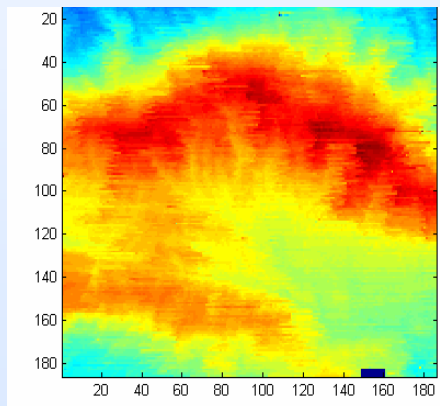
## SIMULATED MTI CLUTTER MAPS



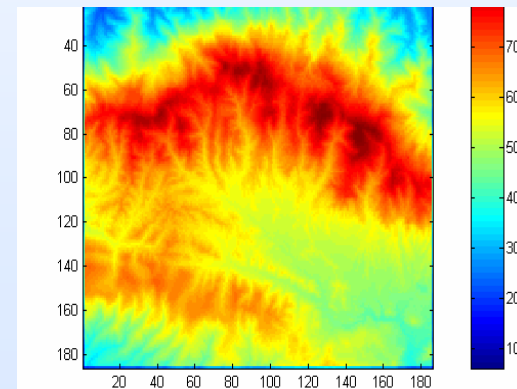
LOOK-1



LOOK-2



ESTIMATED DEM

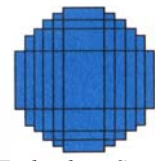


LEVEL-3 DTED



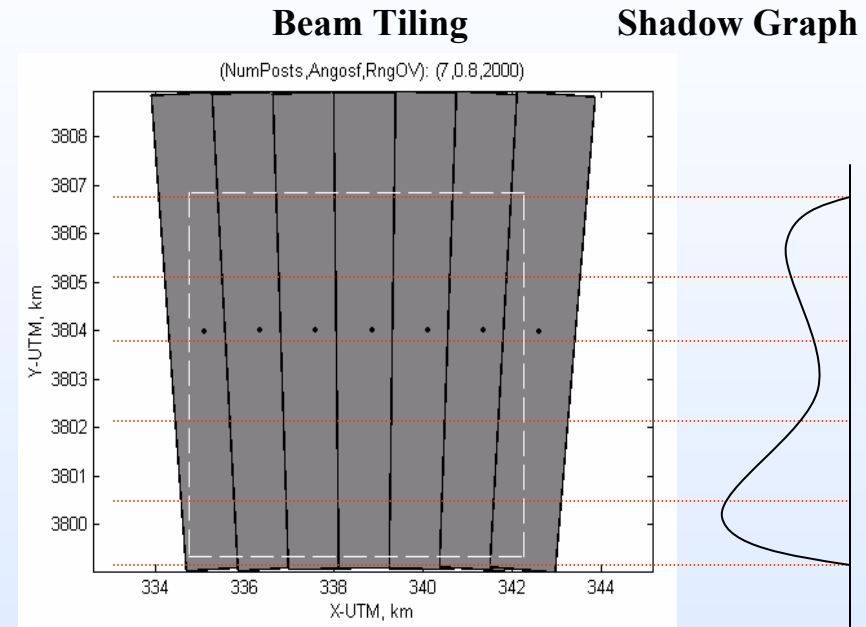


# *Enhancement of MTI Cross-Range Resolution through Tomographic Processing*



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- **Cross-range resolution is much coarser than down-range resolution for typical MTI maps**
  - KASSPER/MCARM = 200x
  - Joint STARS = 20x
- **Averaging MTI maps sharpens cross-range by overlapping footprints at different aspect angles**
  - Effective only for limited range of aspect angles
- **Noncoherent tomography offers greater cross-range resolution enhancement for stereo processing**
  - Form range shadow graph at each aspect angle (radon transform)
  - Filtered back-projection of shadow graphs are accumulated
  - Correlate the sharpened MTI maps to derive height information (stereo processing)

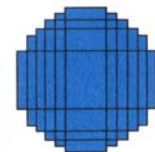




# Examples of Noncoherent Tomographic Processing

## 20-to-1 Cross Range Blurring

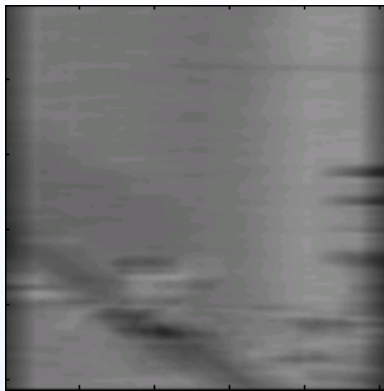
*Ideal Case: No Thermal Noise, Shadowing, or Target Fluctuation with Aspect*



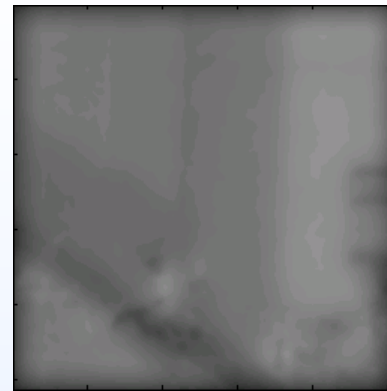
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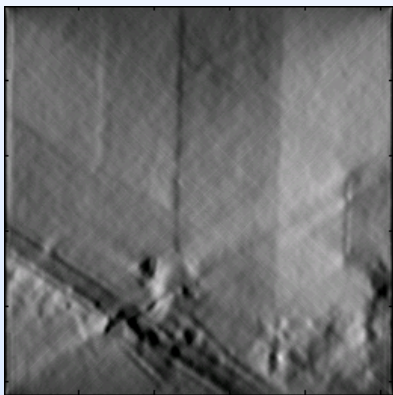
High Resolution SAR Map



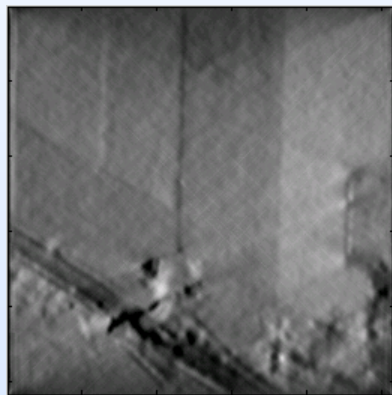
Single-Look MTI Map



Average MTI Map



120 deg



140 deg



160 deg



180 deg

TOMOGRAPHIC  
ANGLE





# *Exploitation of Interferometric Imagery or SAR/Registered DTED*



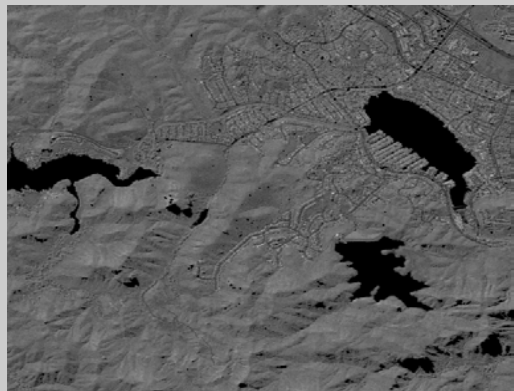
- **Can provide information on strong scatterers that interfere with nearby weak target signals**
  - All discretely are not in database (new structures, parked vehicles, natural objects)
  - Strong distributed terrain backscattering (near-normal orientation, dense vegetation)
- **Requires SAR and GMTI data from same region to investigate concepts such as:**
  - Excising resolution cells with strong clutter in SAR image from secondary data set
  - Adaptive detection thresholding based on SAR amplitude statistics or textural features at corresponding location
  - Prefiltering of strongest clutter regions found in SAR image
  - Select secondary data set based on terrain type determined from SAR
- **Utilizing SAR-based GMTI simulation for algorithm development**



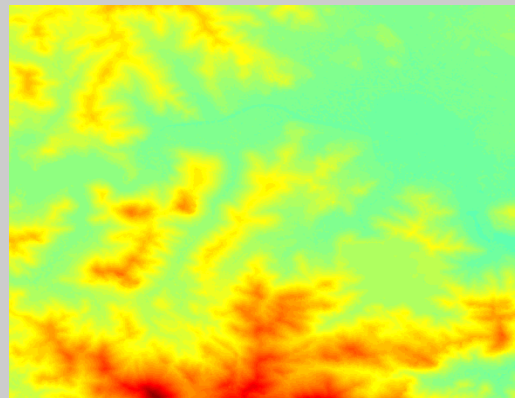




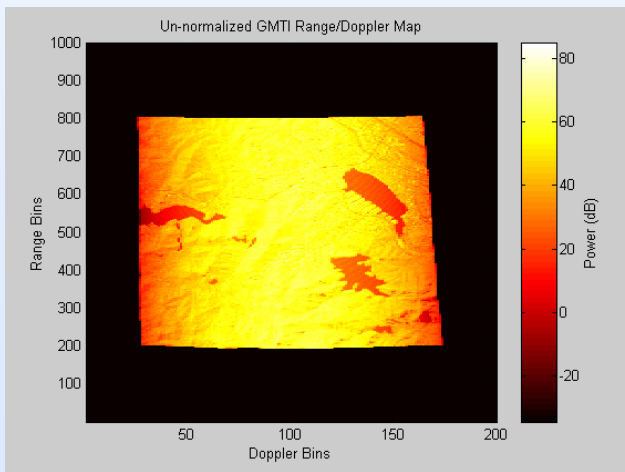
# Example of Using SAR and DTED to Identify Strong Scattering Regions



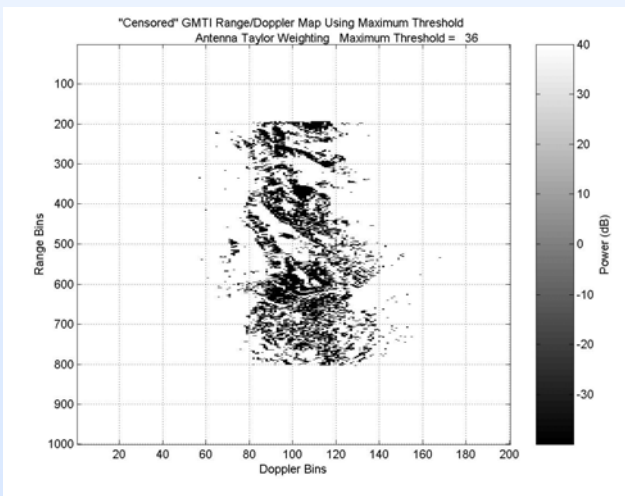
**SAR Imagery: 3 m x 3 m Resolution**



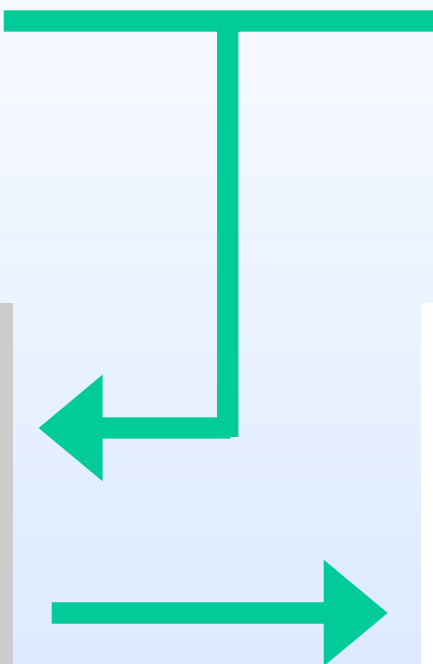
**Level-3 DTED**



**Synthesized GMTI Clutter Map:  
10 m Range, 5 Hz Doppler Resolution**

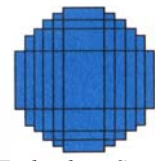


**GMTI Range/Doppler Cells Whose Corresponding  
SAR Magnitude Exceeds Threshold**





# *Advanced Angle/Doppler Estimation Techniques*



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- **Improve geolocation of large discretely and movers to enhance STAP performance**
  - Excise corresponding resolution cells or prefilter these strong returns from secondary data set
  - Predict detections from azimuth and Doppler sidelobes to reject false alarms
- **Investigating several methods to operate with full or reduced dimension STAP**
  - MLE, Minimum Variance Estimator, and Prony's method
  - Compare with conventional beam and filter splitting
- **Associating STAP MLE detections with ground truth from 2003 KASSPER data cube for preliminary investigation**
  - Full dimension STAP with censoring of discretely and movers
  - PRI-staggered, post-Doppler STAP architecture



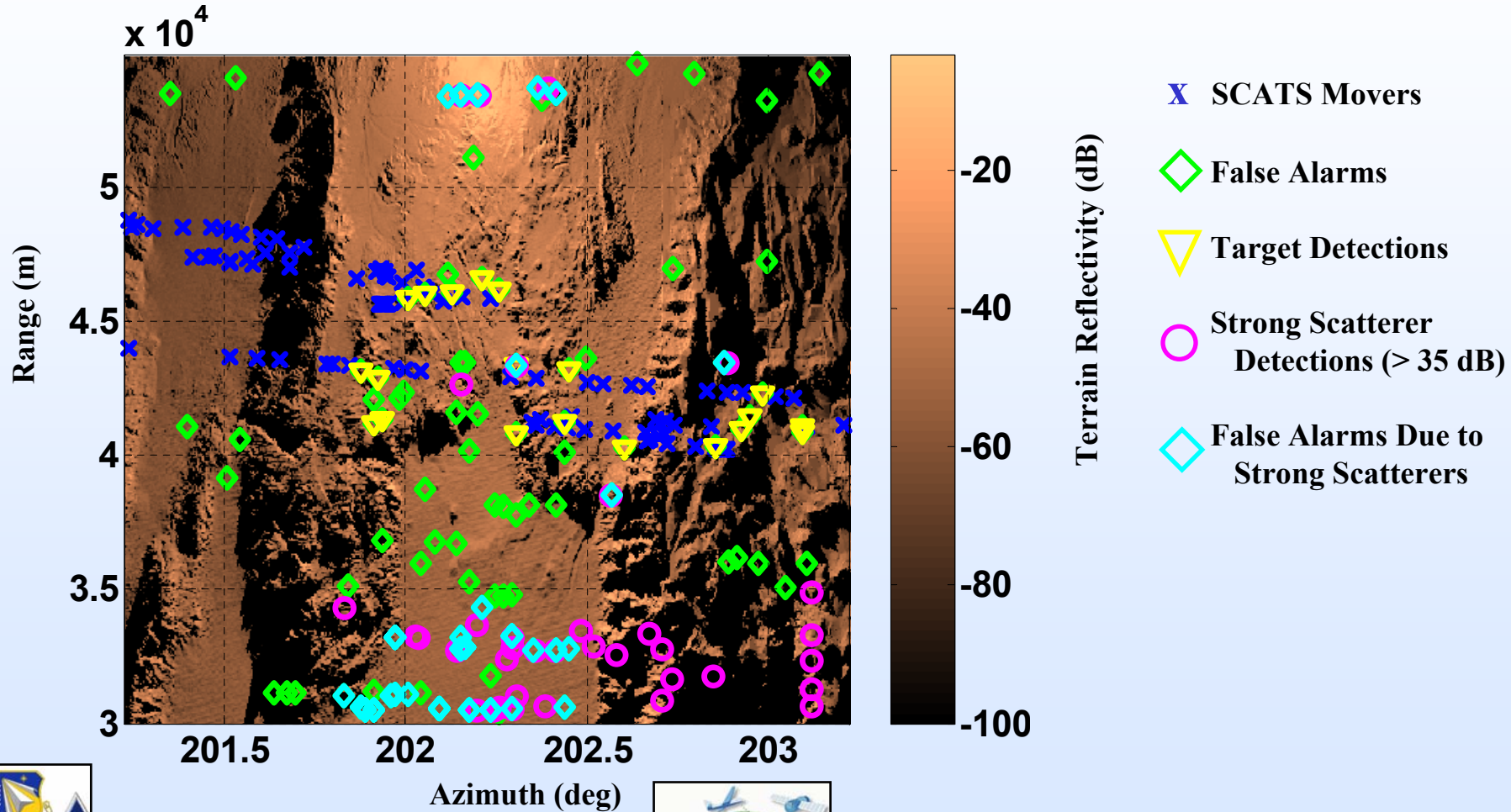




# Knowledge of Terrain Cell Reflectivity Aids in Associating False Alarms with Strong Distributed Clutter

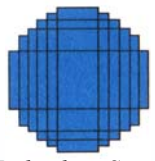


Range vs. Azimuth: SCATS Ground Truth, MLE, 5 PRI Stagers, Discrete/Target Censoring,  $10^{-7}$  Pfa





## *Planned Work*



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- **Quantify the benefits of improved knowledge on STAP performance**
  - Increased DEM accuracy from stereo or interferometric processing
  - Reliable LU/LC map from GMTI clutter or registered SAR imagery
  - Improved location of discretely and terrain backscattering
- **Evaluate sensor, processing and platform requirements for knowledge acquisition**
  - Determine optimal GMTI dwell length, aperture size, and flight profile
- **Demonstrate stereo DEM generation from measured clutter data**
  - Joint STARS flights with elevation aspect change
- **Use GMTI simulation to develop techniques that exploit SAR/DTED information and enhance STAP performance**
- **Investigate array calibration techniques**
  - Exploit knowledge of distributed/discrete clutter or active RF sources
  - Correct channel amplitude and phase imbalances

